

Learning Dictionary via Subspace Segmentation for Sparse Representation

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2 Sparse Representation via Subspace Segmentation

- Structured Representation Model
- Subspace Segmentation Algorithm
- Dictionary Constructing Algorithm

3 Experimental Results

- Sparse Representation
- Image Patch Denoising

4 Summary

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Image patch $y \in \mathbb{R}^n$

Overcomplete dictionary $\mathbf{D} = \{d_j\}_{j=1}^m$

Sparsity L

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$$|\text{supp}(x)| \leq L \ll n \leq m \tag{2}$$

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Putting structure into sparse model: The atom selection choice Λ is restrict to be a subset of Γ_k , where Γ_k is one of the K subsets of $\{1, 2, \dots, m\}$ with $|\Gamma_k| \ll m$.

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Toy example:



$m = 5$, $K = 2$, $\Gamma_1 = \{1, 2, 3, 4\}$ and $\Gamma_2 = \{1, 2, 5\}$. For $L = 3$, the choice number decrease from $\binom{5}{3} = 10$ to $\binom{4}{3} + \binom{3}{3} = 5$.

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Learning dictionary under the structured model:

- ① *Subspace segmentation*: Segmenting the training data that lie on different subspaces.
- ② *Dictionary construction*: Determine the shared atoms of different subspaces.

Subspace Segmentation Algorithm



Prior work for segmentation:

- *expectation maximization*(EM)
- K-means
- K-subspaces
- Generalized PCA

Our segmentation algorithm is a modification of the K-subspaces algorithm.

The K-subspaces Clustering Algorithm



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1 Initialization

Start with a random collection $\{S_1, \dots, S_K\}$ of K subspaces of dimension d , where $S_k \subset \mathbb{R}^n$. Each subspace S_k is represented by one of its orthonormal basis, U_k (represented as a n -by- d matrix).

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2 Cluster Assignment

We define an operator $P_k = I_{n \times n} - U_k U_k^T$ for each subspace S_k . Each sample y_i is assigned a new label $L(y_i)$ such that

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3 Cluster Update

Let S'_k be the set of samples labeled as k . We apply SVD (Singular Value Decomposition) to samples in S_k to form the new basis U'_k . Stop when $S'_k = S_k$ for all k . Other wise, go to Step 2.

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$$L'(y_i) = \operatorname{argmin}_k \|P_k y_i\|_2^2 + \lambda d_k. \quad (4)$$

The left part restricts the approximation error and the right part makes the representation as sparse as possible.

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In the Cluster Update step, we retain d_k columns for the new basis U'_k .

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Iteration:

- 1 $K = K + 1$.
- 2 Find the largest neighborhood Ω in Y .
- 3 Find the subspace with base U_K that most data in Ω lie on.
- 4 Set all the data lie on U_K in Y to be S_K .
- 5 $Y = Y - S_K$.

Dictionary Constructing Algorithm

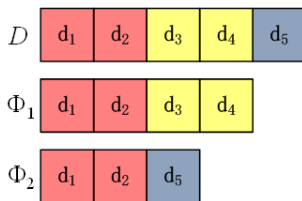


Task: Given a segmentation $\{S_1, \dots, S_K\}$ and its dimension set $\{d_1, \dots, d_K\}$, constructing the dictionary \mathbf{D} .

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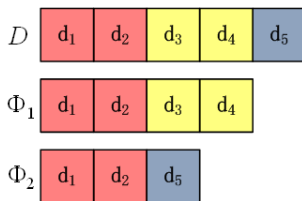
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$\mathbf{D} = (\mathbf{B}_1 | \mathbf{B}_2 | \mathbf{B}_3)$ with $\Phi_1 = (\mathbf{B}_1 | \mathbf{B}_2)$ and $\Phi_2 = (\mathbf{B}_1 | \mathbf{B}_3)$.

$$\begin{cases} (\mathbf{B}_1 | \mathbf{B}_2) = Q_1 U_1 \\ (\mathbf{B}_1 | \mathbf{B}_3) = Q_2 U_2 \end{cases} \quad (5)$$

\mathbf{B}_1 can be obtained according to the SVD result of $U_1^T U_2$.

Similarly, for $K > 2$. For $k = 1$ to K .

Suppose

$$\mathbf{D}^{(k-1)} = (\mathbf{B}_1 | \cdots | \mathbf{B}_{n_{k-1}}).$$

We obtain \mathbf{B}'_i by computing SVD for $\mathbf{B}_i^T U_k$, for $i = 1, \dots, n_{k-1}$.

$$\begin{aligned} \mathbf{D}^{(k)} = & (\mathbf{B}'_1 | \cdots | \mathbf{B}'_{n_{k-1}} | \\ & \mathbf{B}_1 / \mathbf{B}'_1 | \cdots | \mathbf{B}_{n_{k-1}} / \mathbf{B}'_{n_{k-1}} | \\ & U_k / \mathbf{B}'_1 / \cdots / \mathbf{B}'_{n_{k-1}}) \end{aligned} \quad (6)$$

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Sparse Representation

We choose 10000 patches of size 8×8 from a given image for representation.

$L = \frac{\sum_{k=1}^K |S_k| d_k}{\sum_{k=1}^K |S_k|}$: the average number of atoms used.

n_K : the dictionary size.

Table 1: Dictionary learning results.

image	K	L	n_K	RMSE
lena	14	7.65	95	4.23
barbara	18	13.37	193	4.53
boat	21	13.32	205	4.86
peppers	18	7.87	147	4.33
man	14	24.22	211	4.87

Image Patch Denoising



For a given image I and the noisy version $I' = I + \varepsilon$, where $\varepsilon_{ij} \sim N(0, \sigma^2)$ is white noise, we collect all the 8×8 patches to be $\{y_i\}$ and $\{y'_i\}$. Total number of signal in $\{y_i\}$ is about 250000.

Training data: Randomly selected 10000 patches from $\{y_i\}$.

For denoising: All patches in $\{y'_i\}$.

Table 2: Denoising RMSE under different σ , the column from left to right represents K-SVD, SSMS and the proposed algorithm respectively. The smallest one is bolded.

image	$\sigma = 10$			$\sigma = 20$		
lena	6.20	6.50	5.60	9.18	9.63	8.30
barbara	7.48	7.84	6.59	11.52	11.93	10.22
boat	7.55	7.94	6.93	11.18	11.67	10.31
peppers	6.52	6.76	6.03	9.22	9.72	8.33
man	8.36	9.03	8.10	12.40	13.11	12.01

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We proposed a new algorithm for dictionary learning.

The learned dictionary is strongly structured with its size adaptive to the training data.

Initial supportive experiments showed its superiority and potential in image processing related applications.